

Figure 1: The Basic Open Re-entrant Line

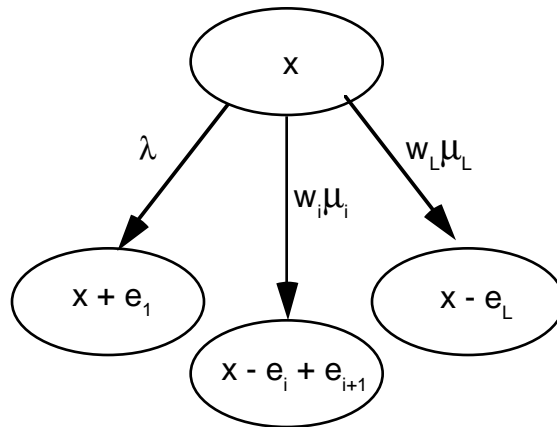


Figure 2: State Transition Diagram for Basic Open Re-entrant Line

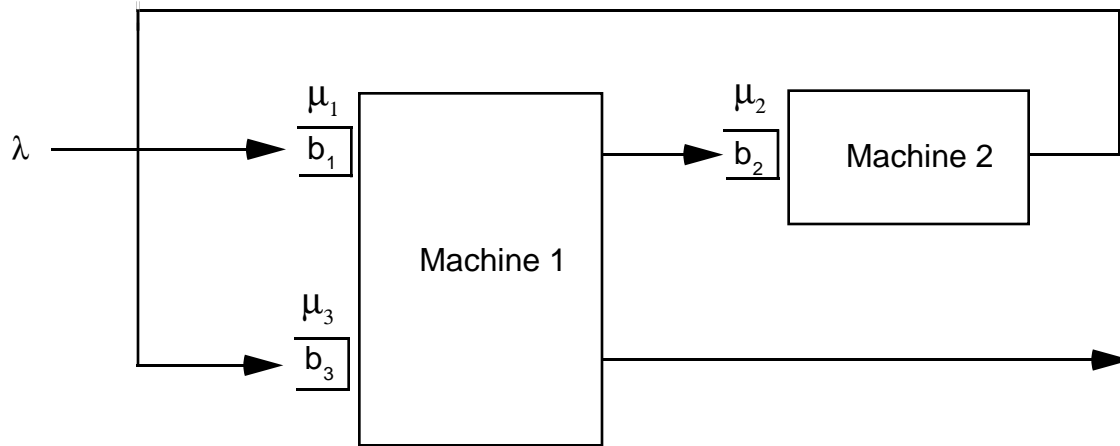


Figure 3: Example of Sections 7 and 10

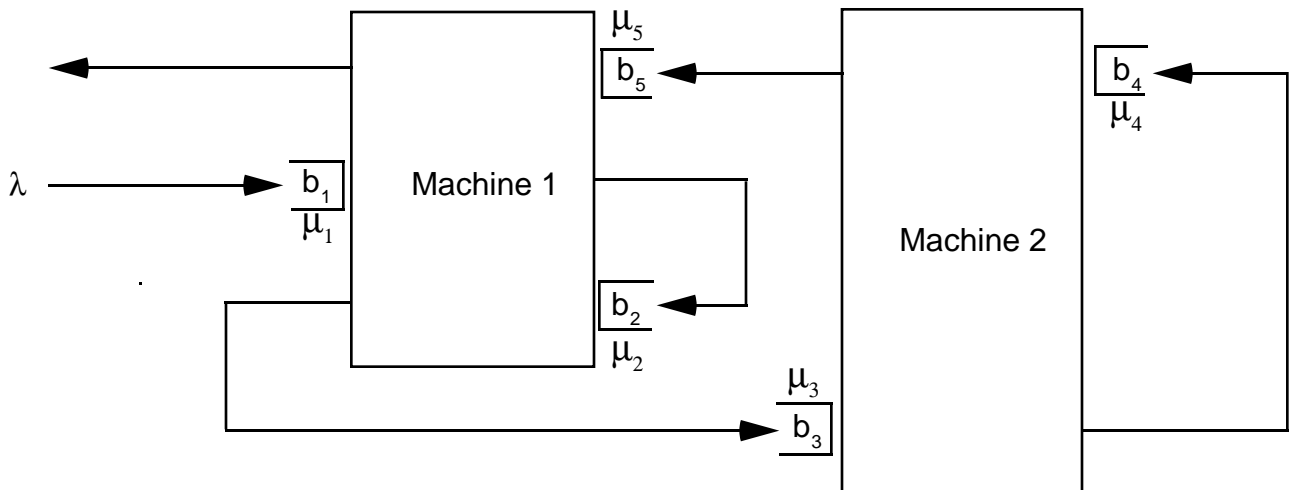


Figure 4: Dai-Wang Example of Section 8

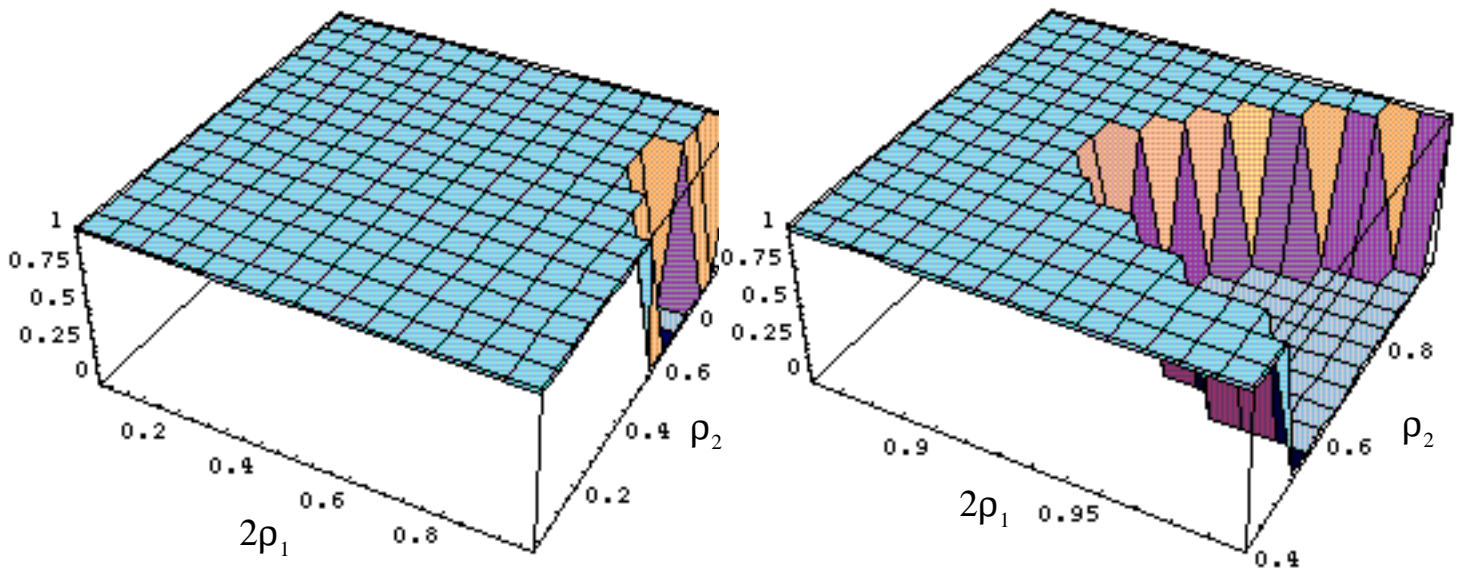


Figure 5: Value of LP for All Non-Idling, Non-Interruptive Policies in Example of Section 10.
 The figure on the right is a more detailed view of one corner of the figure on the left.

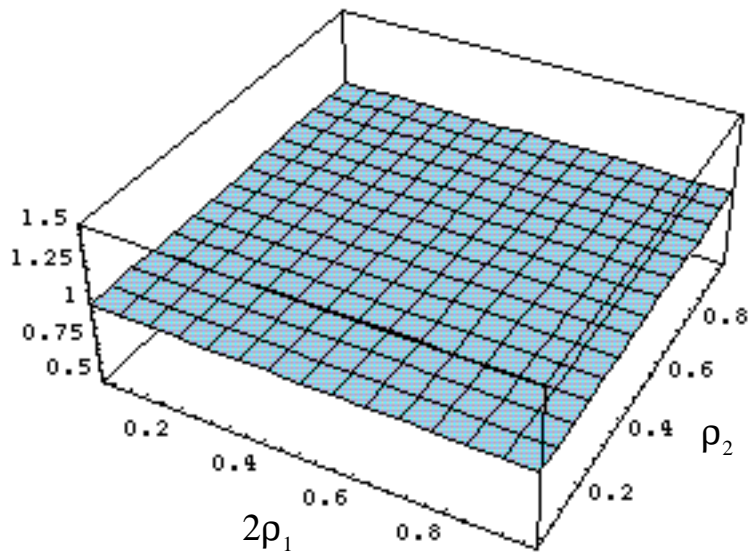


Figure 6: Value of LP for Example of Section 10, for the LBFS policy, and for the FBFS policy.

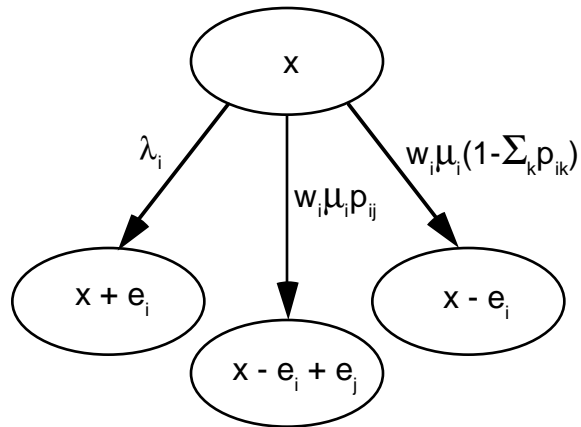


Figure 7: State Transition Diagram for General Queueing Network of Section 12.

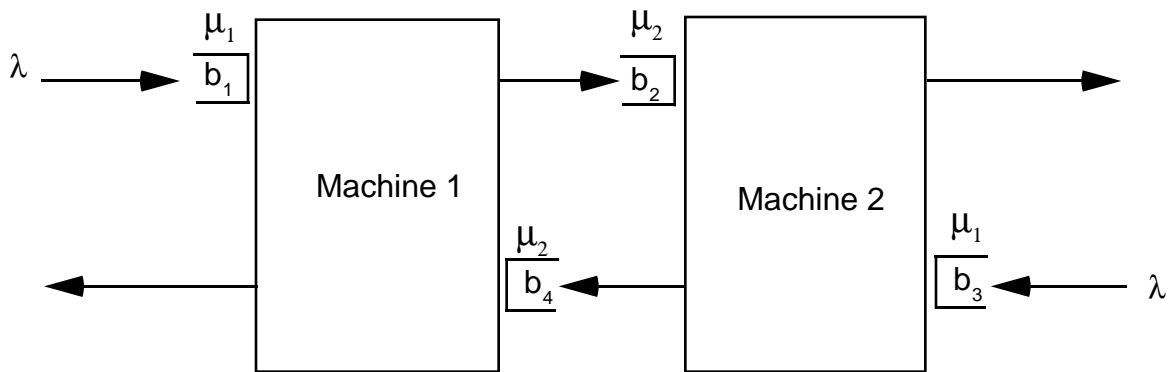


Figure 8: The Rybko-Stolyar Example of Section 13.

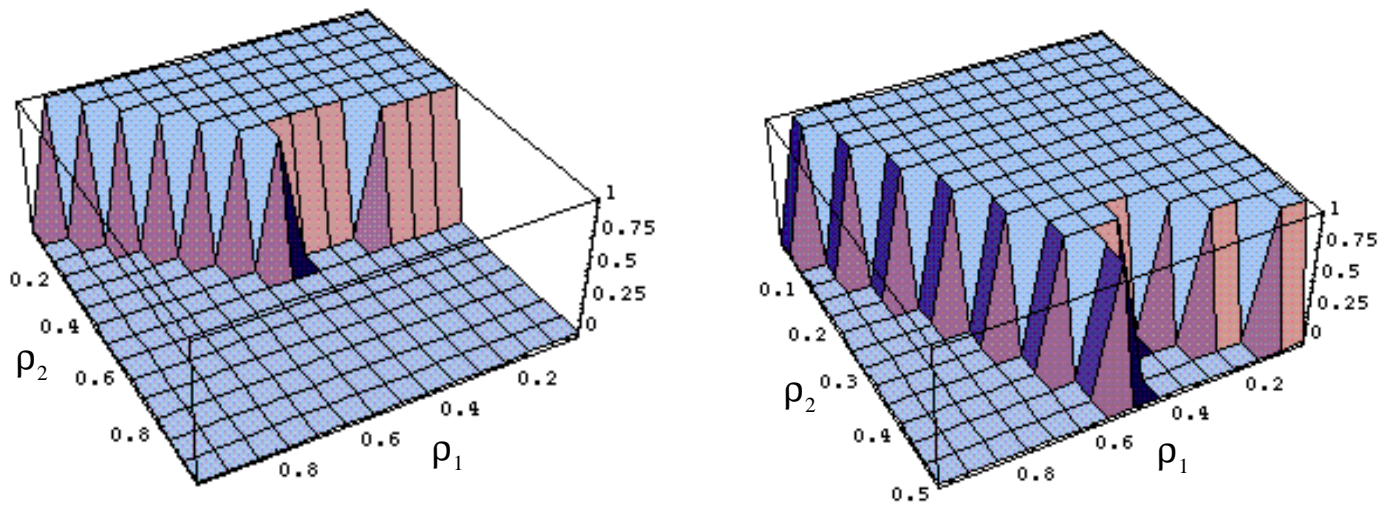


Figure 9: Value of the Linear Program for Rybko-Stolyar Example of Section 13. The figure on the right is a more detailed view of one portion of the figure on the left.

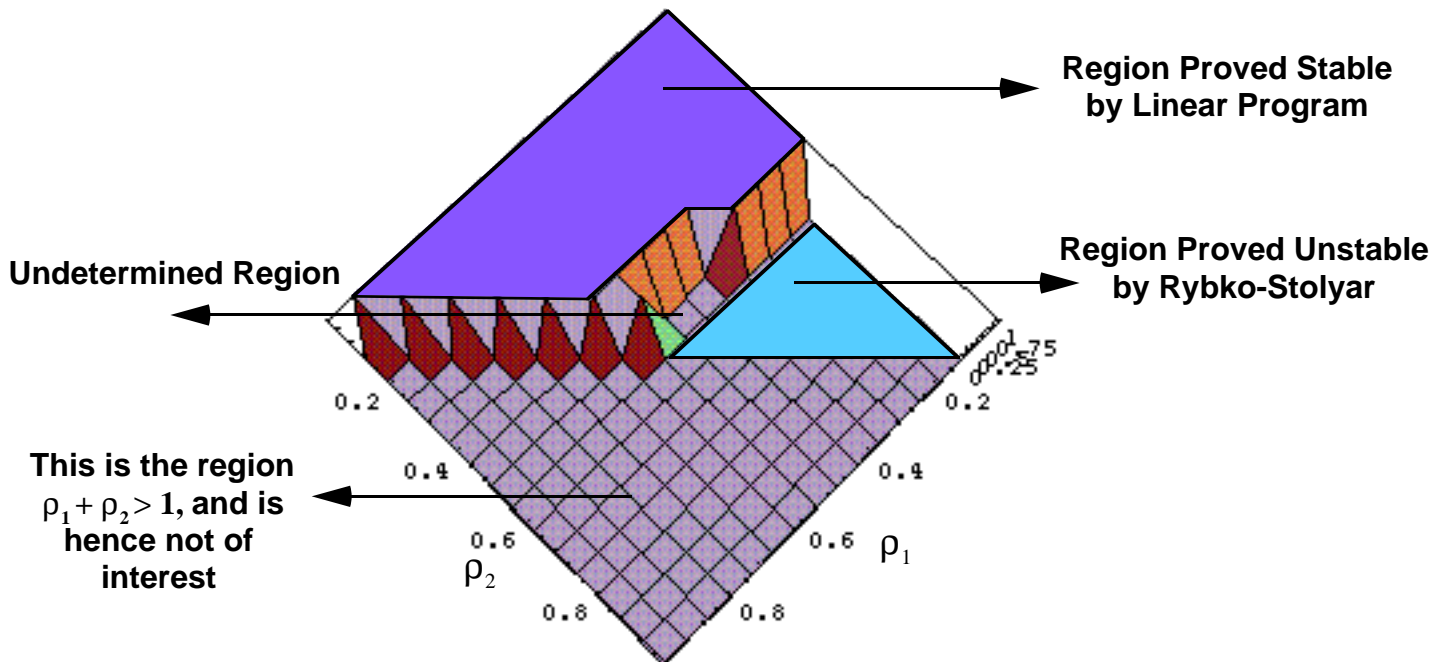


Figure 10: Stable, Unstable, and Undetermined Regions for Rybko-Stolyar Example